## Quicksort

Chapter 7

### Sorting

- What's the running time for:
  - Insertion Sort
  - Merge Sort
  - Heapsort
- Which of these algorithms sort in place?

### Quicksort

- The Basic version of quicksort was invented by C. A. R. Hoare in 1960
- Divide and Conquer algorithm
- In practice, it is the fastest in-place sorting algorithm

### Divide and Conquer

 Divide: Partition the array into two subarrays around a pivot x such that elements to the left are <= x and elements to the right are >= x



- Conquer: Recursively sort the two subarrays
- Combine: Trivial!

Good
Key? Partitioning
Subroutine!

### Quicksort Pseudocode

### QUICKSORT(A, p, r)

```
Quicksort(A, p, r) // A:Array; p,r: integer indexes

1  if p < r
2   q = Partition(A, p, r);

3   Quicksort(A, p, q-1);

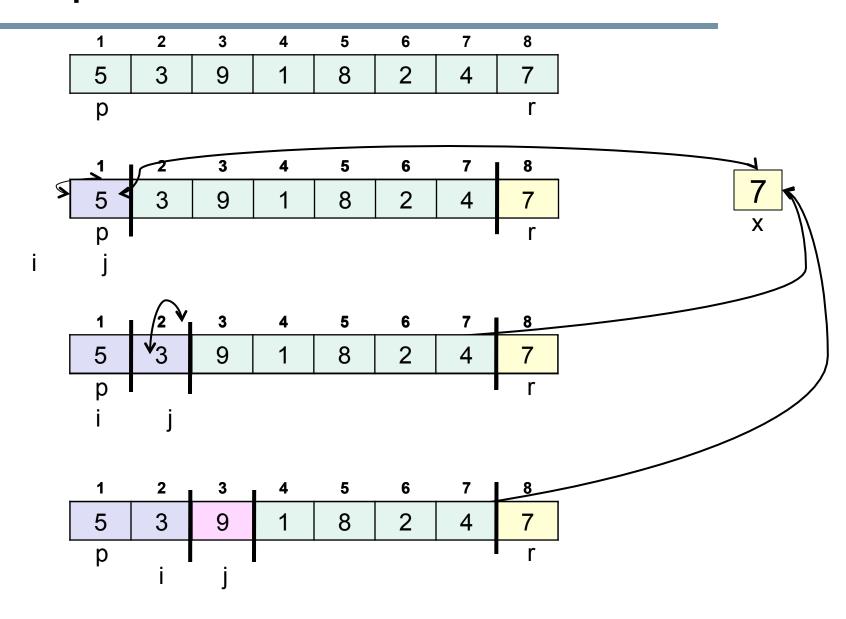
4   Quicksort(A, q+1, r);</pre>
```

What's the call to sort the entire array?

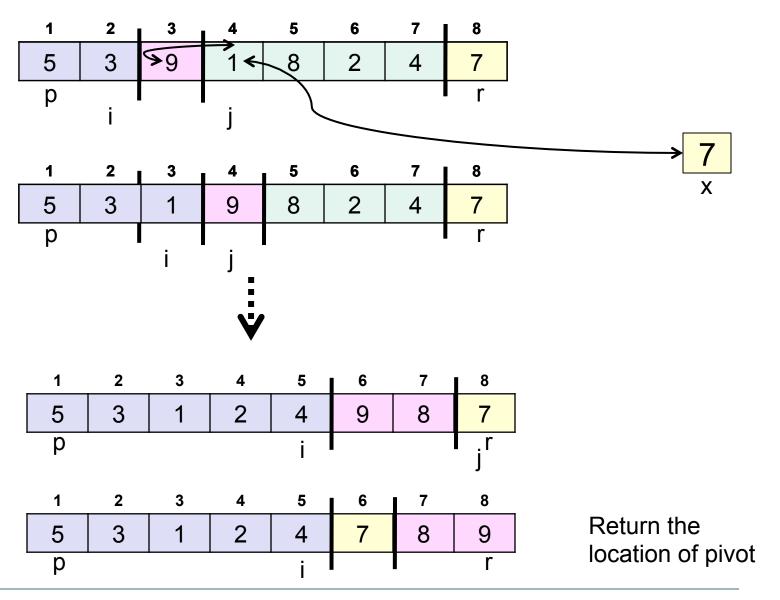
# Partitioning the Array

	Partition(A,p,r) // A:Array; p,r: integer indexes
1	x = A[r]
2	i = p - 1
3	for j = p to r-1
4	if A[j] <= x
5	i = i + 1
6	swap(A[i], A[j])
7	swap (A[i+1], A[r])
8	return i+1

### Example

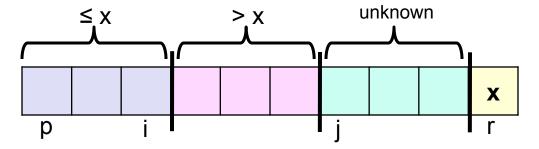


### Example



#### Correctness of Partition

 During the execution of PARTITION there are four distinct sections of the array:



### Exercise - Partition the Following

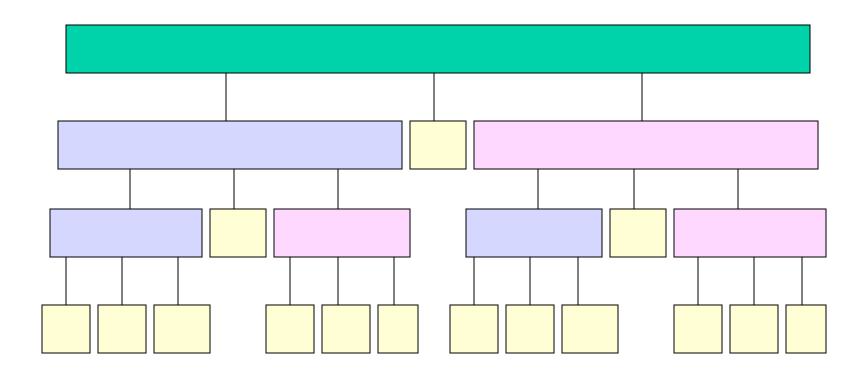
44	75	23	13	55	12	61	77	33	11
44	13	23	43	33	12	04	11	<b>33</b>	41

### **Analysis of Partition**

What is the running time of PARTITION?

	Partition(A,p,r) // A:Array; p,r: integer indexes
1	x = A[r]
2	i = p - 1
3	for j = p to r-1
4	if A[j] <= x
5	i = i + 1
6	swap(A[i], A[j])
7	swap (A[i+1], A[r])
8	return i+1

## Quicksort in Action



#### Exercise

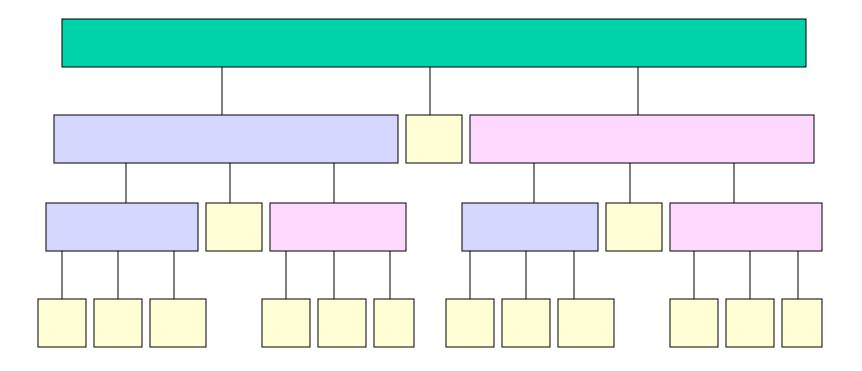
Sort the following array using quicksort

3 4 2 5 1

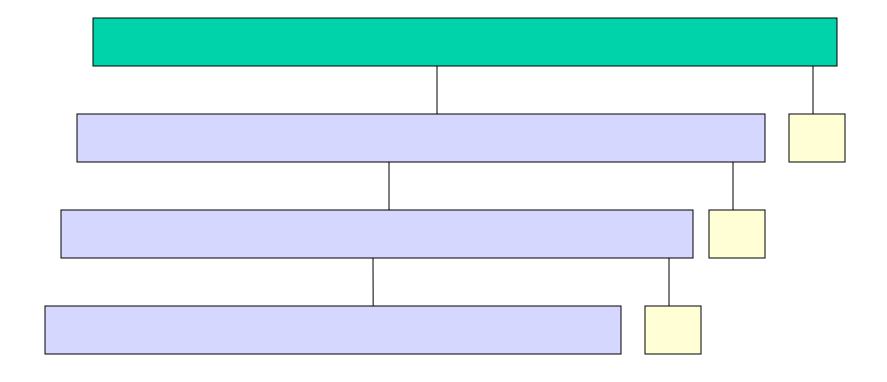
### Performance of Quicksort

- What does the performance of quicksort depend on?
- What would give us the best case?

## Best Case of Quicksort



## Worst Case of Quick Sort



### Quicksort Analysis

- To justify its name, Quicksort had better be good in the average case.
- Showing this requires some intricate analysis.

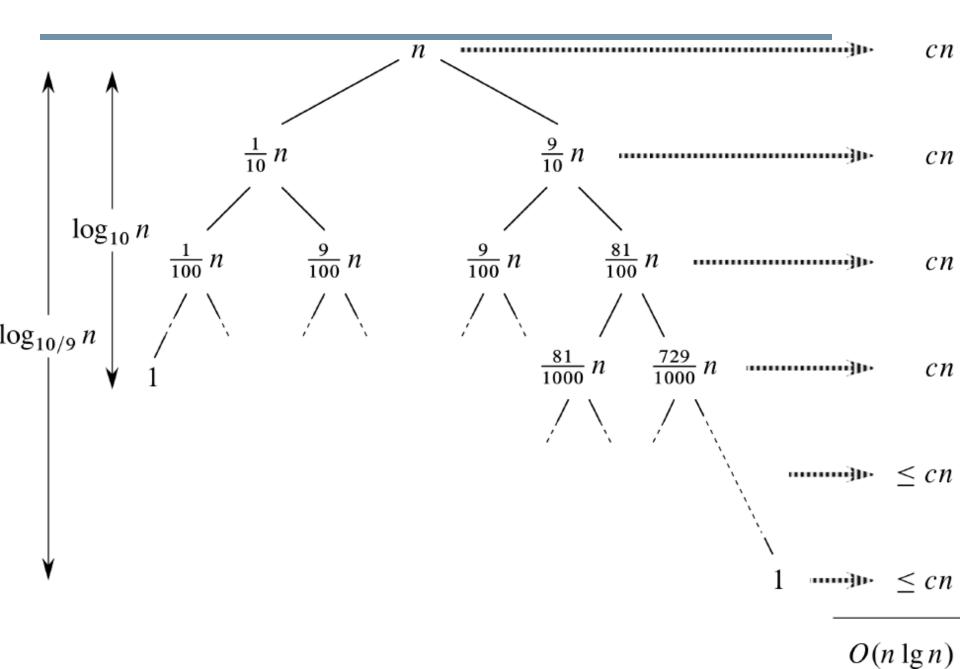
### Average Case Analysis

- Let's look at this by intuition
- Running quicksort on a random array is likely to produce a mix of balanced and unbalanced partitions
- It has been shown that 80% of the time partition produces good splits and 20% of the time it produces bad splits

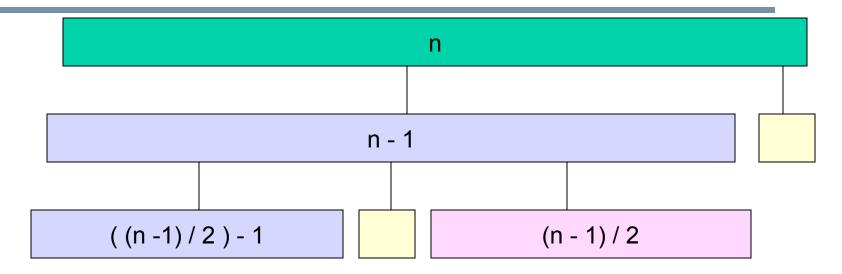
### Assume 9-1 split, p 176

- Assume each partition is a 9 to 1 split.
  - constant proportionality
- What is the recurrence?

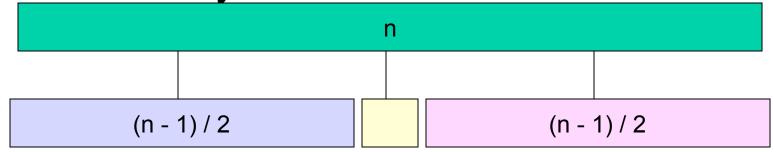
Fig 7.4 What does the recursion tree look like (9-1 split)?



### Average Case Analysis



This is really no different than:



 Thus, the O(n -1) of the bad split can be absorbed into the O(n) of the good split

### Average Case Analysis

- The running time of quicksort when alternating good and bad splits is like the running time for good splits alone
- O(n lg n) but with a slightly larger constant hidden by the O-notation

### Random Partition, p 179

	Randomized-Partition(A, p, r)			
1	i = RANDOM(p,r)			
2	swap (A[r], A[i])			
3	return PARTITION(A, p, r)			

### Hoare Partition, p 185

	HoareParition(A,p,r)
1	x = A[p]
2	i = p -1
3	j = r + 1
4	while TRUE
5	do
6	j=j-1
7	while(A[j] > x)
8	do
9	i = i+1
10	while( $A[i] < x$ )
11	if ( i < j)
12	swap (A[i], A[j])
13	else return j