
Optimal Binary Search Trees

Chapter 15

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Balanced BST

- Are balanced binary search trees always the most efficient search trees?
- Yes! But only if every key is equally probable

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Example

- Dictionary for spell-checking
 - What if the root of a balanced tree is "panentheism"?
 - Occurrence in ordinary text is very low
 - Most searches will waste at least one comparison
 - What if the most common words ("a", "an", "the", etc.) are the leaves?
- Balanced binary search tree is not always the most efficient
 - Problem is that not all words are equally likely

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Optimal BST

- In optimal BSTs we store the probability of each node along with its key
- Given sequence $K = \langle k_1, k_2, \dots, k_n \rangle$ of n distinct keys, sorted ($k_1 < k_2 < \dots < k_n$)
- Want to build a binary search tree from the keys
- For k_i , have probability p_i that a search is for k_i
- Want BST with minimum expected search cost

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Cost of a Search

- Actual cost = # of items examined.
- For key k_i , cost = $\text{depth}_T(k_i) + 1$, where $\text{depth}_T(k_i)$ = depth of k_i in BST T .

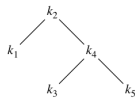
E [search cost in T]

$$\begin{aligned}
 &= \sum_{i=1}^n (\text{depth}_T(k_i) + 1) \cdot p_i \\
 &= \sum_{i=1}^n \text{depth}_T(k_i) \cdot p_i + \sum_{i=1}^n p_i \\
 &= 1 + \sum_{i=1}^n \text{depth}_T(k_i) \cdot p_i
 \end{aligned}$$

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Example

i	1	2	3	4	5
p_i	.25	.2	.05	.2	.3



i	$\text{depth}_T(k_i)$	$\text{depth}_T(k_i) \cdot p_i$
1	1	.25
2	0	0
3	2	.1
4	1	.2
5	2	.6
		1.15

Therefore, E [search cost] = 2.15.

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Another Example

i	1	2	3	4	5
p_i	.25	.2	.05	.2	.3

i	$\text{depth}_T(k_i)$	$\text{depth}_T(k_i) \cdot p_i$
1		
2		
3		
4		
5		

E [search cost] =

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Observations

- Optimal BST might not have smallest height.
- Optimal BST might not have highest probability key at root.

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Exhaustive Checking

- Construct each n -node BST.
- For each, put in keys.
- Then compute expected search cost.
- But there are $\Omega(4^n / n^{3/2})$ different BSTs with n nodes.

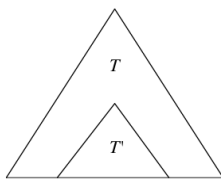
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Solution

- Dynamic Programming
 1. Characterize the structure of an optimal solution
 2. Recursively define the value of an optimal solution
 3. Compute the value of an optimal solution bottom-up
 4. Construct an optimal solution from the computed information

Step 1: Optimal Solution

- Consider any subtree of a BST. It contains keys in a contiguous range k_i, \dots, k_j for some $1 \leq i \leq j \leq n$.



If T is an optimal BST and T contains subtree T' with keys k_i, \dots, k_j , then T' must be an optimal BST for keys k_i, \dots, k_j .

Step 1: Optimal Solution

- Use optimal substructure to construct an optimal solution to the problem from optimal solutions to subproblems:
- Given keys k_i, \dots, k_j (the problem).
- One of them, k_r , where $i \leq r \leq j$, must be the root.
- Left subtree of k_r contains k_i, \dots, k_{r-1} .
- Right subtree of k_r contains k_{r+1}, \dots, k_j .

Step 1: Optimal Solution

- If
 - we examine all candidate roots k_r , for $i \leq r \leq j$, and
 - We determine all optimal BSTs containing k_i, \dots, k_{r-1} and containing k_{r+1}, \dots, k_j ,
- *then we're guaranteed to find an optimal BST for k_i, \dots, k_j*

Step 2: Recursive Solution

Subproblem domain:

- Find optimal BST for k_i, \dots, k_j , where $i \geq 1, j \leq n, j \geq i - 1$.
- When $j = i - 1$, the tree is empty.

Define $e[i, j]$ = expected search cost of optimal BST for k_i, \dots, k_j .

If $j = i - 1$, then $e[i, j] = 0$.

If $j \geq i$,

- Select a root k_r , for some $i \leq r \leq j$.
- Make an optimal BST with k_i, \dots, k_{r-1} as the left subtree.
- Make an optimal BST with k_{r+1}, \dots, k_j as the right subtree.
- Note: when $r = i$, left subtree is k_i, \dots, k_{i-1} ; when $r = j$, right subtree is k_{j+1}, \dots, k_j .

Step 2

When a subtree becomes a subtree of a node:

- Depth of every node in subtree goes up by 1.
- Expected search cost increases by

$$w(i, j) = \sum_{l=i}^j p_l \quad (\text{refer to equation } (*)) .$$

Step 2

If k_r is the root of an optimal BST for k_i, \dots, k_j :

$$e[i, j] = p_r + (e[i, r - 1] + w(i, r - 1)) + (e[r + 1, j] + w(r + 1, j)).$$

But $w(i, j) = w(i, r - 1) + p_r + w(r + 1, j)$.

Therefore, $e[i, j] = e[i, r - 1] + e[r + 1, j] + w(i, j)$.

This equation assumes that we already know which key is k_r .

We don't.

Try all candidates, and pick the best one:

$$e[i, j] = \begin{cases} 0 & \text{if } j = i - 1, \\ \min_{i \leq r \leq j} \{e[i, r - 1] + e[r + 1, j] + w(i, j)\} & \text{if } i \leq j. \end{cases}$$

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Step 3

OPTIMAL-BST(p, q, n)

let $e[1..n+1, 0..n]$, $w[1..n+1, 0..n]$, and $root[1..n, 1..n]$ be new tables

for $i = 1$ to $n + 1$

$e[i, i - 1] = 0$

$w[i, i - 1] = 0$

for $l = 1$ to n

 for $i = 1$ to $n - l + 1$

$j = i + l - 1$

$e[i, j] = \infty$

$w[i, j] = w[i, j - 1] + p_j$

 for $r = i$ to j

$t = e[i, r - 1] + e[r + 1, j] + w[i, j]$

 if $t < e[i, j]$

$e[i, j] = t$

$root[i, j] = r$

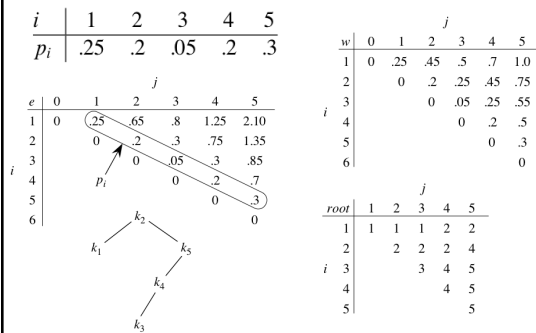
return e and $root$

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Example



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Step 4

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CONSTRUCT-OPTIMAL-BST(root)
  r = root[1, n]
  print "k"r "is the root"
  CONSTRUCT-OPT-SUBTREE(1, r - 1, "left", root)
  CONSTRUCT-OPT-SUBTREE(r + 1, n, "right", root)

CONSTRUCT-OPT-SUBTREE(i, j, dir, root)
  if i ≤ j
    t = root[i, j]
    print "k", "is" dir "child of k"r
    CONSTRUCT-OPT-SUBTREE(i, t - 1, "left", root)
    CONSTRUCT-OPT-SUBTREE(t + 1, j, "right", root)
    
```

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Another Example

<i>i</i>	A	B	C	D
<i>p_i</i>	0.1	0.2	0.4	0.3

<i>e</i>					

<i>w</i>					

<i>root</i>				

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