



CS430 Computer Architecture

Spring 2015

Chapter 12

Types of Operations

- Data Transfer - copies data from a source operand into a destination operand
- x86 Examples (Reference: <http://zeus.cs.pacificu.edu/ryand/cs320/2005/cs320.html>)
 - `mov ax,1` ; move 1 into ax
 - `movzx ax, 10000000b` ; mov 128 zero-extended into ax
 - `movsx ax, 10000000b` ; mov -128 sign-extended into ax
 - `push ebx` ; push 32-bit contents of ebx onto the stack
 - `pop edx`

Types of Operations

- Arithmetic - perform some arithmetic calculation and in the case where the processor has a flags register, sets the flags accordingly
- x86 Examples
 - `add ax,bx ; ax<-ax+bx`
 - `sub ax,1 ; ax<-ax-1`
 - `inc cx`
 - `dec cx`

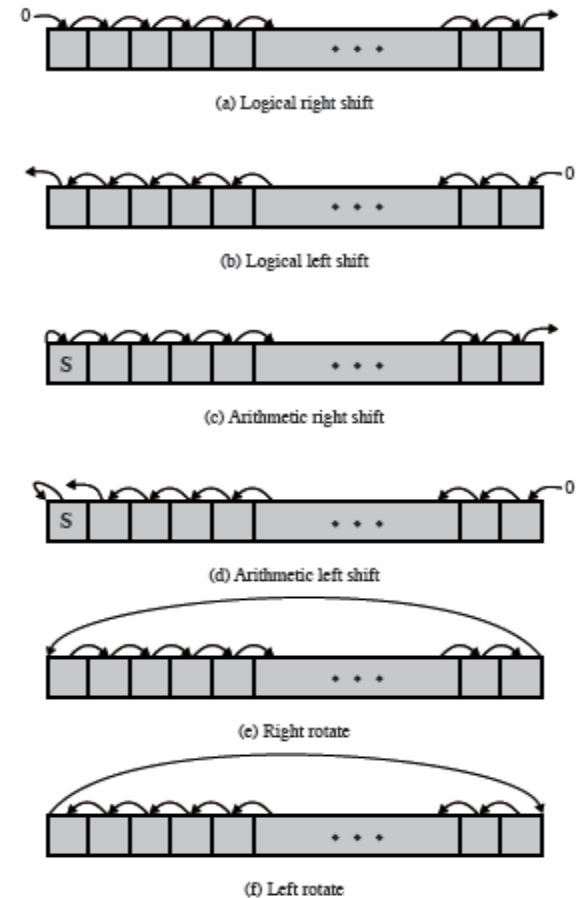
Types of Operations

- Logical - instructions used to do some kind of bit manipulation
- x86 Examples
 - `and bh,0fh`
 - `or ax,10h`
 - `xor ax,bx`

Types of Operations

- More Logical

- `shr ax,1 ; (a)`
- `shl ax,1 ; (b)`
- `sar bh,1 ; (c)`
- `sal bh,1 ; (d)`
- `ror edx,1 ; (e)`
- `rol edx,1 ; (f)`



Types of Operations

- Transfer of Control
 - Conditional branch (conditional jump)
 - Unconditional branch
 - Subroutine call
 - Interrupt

Types of Operations

- Conditional branch - branching is conditionally based on some flags register or some status register
- x86 Example
 - `jne top` ; branch to top if ZF = 0
 - `jb top` ; unsigned ... branch to top if not above or equal
; CF = 1
 - `jl top` ; signed ... branch to top if not greater or equal
; SF <> OF

Types of Operations

- Conditional branch
- x86 Example
 - Conditional branch instructions assume a calculation occurred setting flags in the flags register BEFORE the branch occurs
 - `dec ax`
`jne top`

Types of Operations

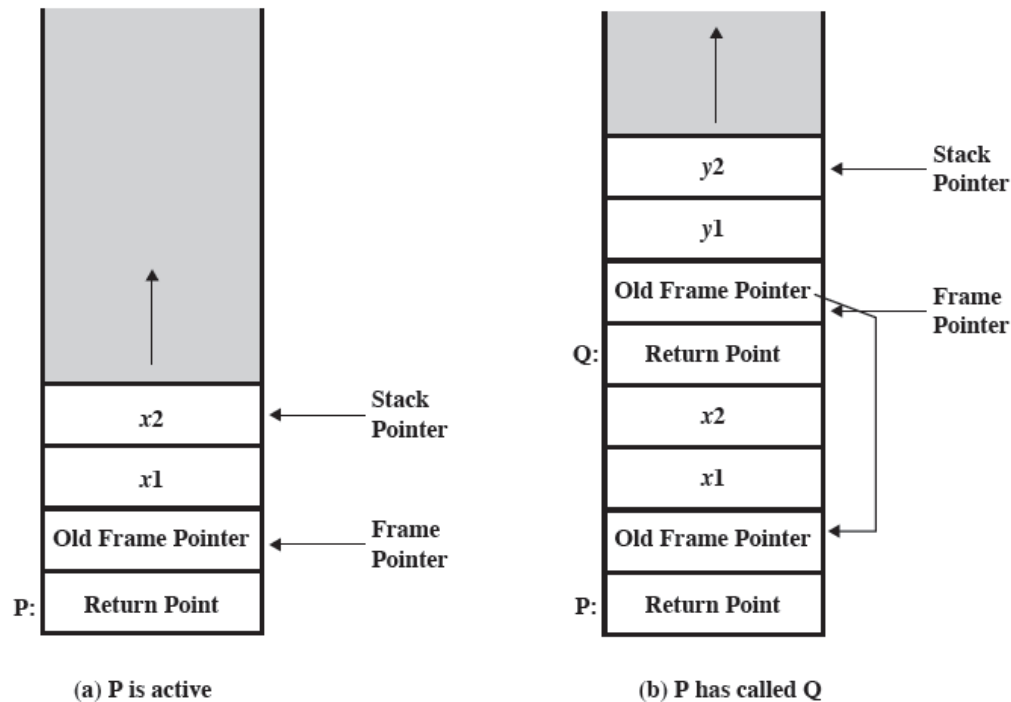
- Unconditional branch - the branch occurs regardless
- x86 Example
 - `jmp top`

Types of Operations

- Subroutine call
- x86 Example
 - `call Foo` ; Foo is an assembly language subroutine

Types of Operations

- Subroutine call - what is happening below?



Types of Operations

- Subroutine call - a typical x86 procedure might begin with the following code:

```
push ebp
```

```
mov ebp, esp
```

```
sub esp, space_for_locals
```

Types of Operations

- Interrupt
- x86 Example
 - `int 0h` ; transfer control to the address stored in the ; interrupt vector table at location 0

Types of Operations

- Interrupt - in x86 Real Mode,
 - an interrupt has an integer in the range of 0-255 called the interrupt type
 - The addresses from 00000 to 003ff are reserved for interrupt vectors
 - An interrupt vector is an address (segment & offset) of a particular interrupt service routine

Types of Operations

- **Interrupt Vector Type**

Interrupt Vector Type	Stored At
0	00000:00003
1	00004:00007
....	
t	4t : 4t+3

- We see that each interrupt vector requires four bytes. The first two bytes contain the offset (bytes reversed). The next two bytes contain the segment (bytes reversed).

Types of Operations

- How do interrupts work? Remember, after most instructions, the microprocessor checks for pending interrupts. If detected, the microprocessor
 - 1) Push the flags register on the stack (why?)
 - 2) Clear the interrupt and trap flags (why?)
 - 3) Push CS
 - 4) Determine the interrupt location based on the type
 - 5) CS = second word of the interrupt vector
 - 6) Push IP
 - 7) IP = first word of the interrupt vector
- The instruction IRET transfers control back to the caller